

Qu_1.

a) $Q = p + iaq$ and $P = (p - iaq)/2ia$ so

$$[Q, P] = ia \times \frac{1}{2ia} - 1 \left(-\frac{1}{2} \right) = 1$$

b) Find $F_2(q, P)$. Need $p = p(q, P)$ and $Q = Q(q, P)$.

$$Q = p + iaq \quad (1)$$

$$2iaP = p - iaq \quad (2)$$

(1)-(2) gives

$$Q - 2iaP = 2iaq \Rightarrow Q = 2ia(P + q) \quad (3)$$

then

$$p = Q - iaq = 2ia(P + q) - iaq = ia(2P + q) \quad (4)$$

$$\begin{aligned} F_2 &= \int p(q, P) dq + f(P) & F_2 &= \int Q(q, P) dP + g(q) \\ &= ia \int (2P + q) dq + f(P) & &= 2ia \int (P + q) dq + g(q) \\ &= ia \left(2Pq + \frac{1}{2} q^2 \right) + f(P) & &= ia(P^2 + 2Pq) + g(q) \end{aligned}$$

comparing

$$F_2(q, P) = ia \left(\frac{1}{2} q^2 + 2qP + P^2 \right)$$

c) Note that $2iaPQ = (p - iaq)(p + iaq) = p^2 + a^2 q^2$, so

$$H = \frac{1}{2} (p^2 + a^2 q^2) = K(Q, P) = iaPQ$$

d) $\dot{Q} = \partial K / \partial P = iaQ$ and $\dot{P} = -\partial K / \partial Q = -iaP$

e) Solutions are $Q(t) = Q_0 e^{iat}$ and $P(t) = P_0 e^{-iat}$

f) Chain rule $du = \sum \left(\frac{\partial u}{\partial q} dq + \frac{\partial u}{\partial p} dp \right) + \frac{\partial u}{\partial t} dt$

$$\frac{du}{dt} = \sum \left(\frac{\partial u}{\partial q} \dot{q} + \frac{\partial u}{\partial p} \dot{p} \right) + \frac{\partial u}{\partial t} = \sum \left(\frac{\partial u}{\partial q} \frac{\partial H}{\partial p} - \frac{\partial u}{\partial p} \frac{\partial H}{\partial q} \right) + \frac{\partial u}{\partial t} = [u, H] + \frac{\partial u}{\partial t}$$

g) Then $\dot{q} = [q, H]$ and $\dot{p} = [p, H]$

Qu_2. Let $x = a + b$ then the translational kinetic energy is $T_{CM} = \frac{m}{2}(\dot{x}^2 + x^2\dot{\phi}^2)$. When ϕ goes from zero to some non-zero value, the small sphere rotates thru an angle of $\phi + \theta$ with respect to the vertical line, hence is rotation rate $\omega = \dot{\theta} + \dot{\phi}$. The rotational kinetic energy is

$$T_{rot} = \frac{1}{2}I\omega^2 = \frac{1}{2}\frac{2}{5}ma^2(\dot{\theta} + \dot{\phi})^2 \quad \text{and} \quad V = mgx \cos \phi$$

Lagrange's equations
$$\frac{d}{dt}\left(\frac{\partial L}{\partial \dot{q}_i}\right) - \frac{\partial L}{\partial q_i} = \sum_l a_{il}\lambda_l$$

Constraints: $dx = 0$ small sphere remains attached
 $bd\phi - ad\theta = 0$ no slipping

$$L = \frac{1}{2}m(\dot{x}^2 + x^2\dot{\phi}^2) + \frac{1}{5}ma^2(\dot{\theta} + \dot{\phi})^2 - mgx \cos \phi$$

$$x: \quad \frac{d}{dt}(m\dot{x}) - (mx\dot{\phi}^2 - mg \cos \phi) = \lambda_1 \quad (1)$$

$$\phi: \quad \frac{d}{dt}(mx^2\dot{\phi} + \frac{2}{5}ma^2(\dot{\theta} + \dot{\phi})) - (mgx \sin \phi) = b\lambda_2 \quad (2)$$

$$\theta: \quad \frac{d}{dt}\left(\frac{2}{5}ma^2(\dot{\theta} + \dot{\phi})\right) = -a\lambda_2 \quad (3)$$

from (2) and (3)

$$mx^2\ddot{\phi} + \frac{2}{5}ma^2(\ddot{\theta} + \ddot{\phi}) - mgx \sin \phi = -\frac{b}{a}\frac{2}{5}ma^2(\ddot{\theta} + \ddot{\phi})$$

but $bd\phi - ad\theta = 0$ implies $\ddot{\theta} = \frac{b}{a}\ddot{\phi}$ so that $a^2(\ddot{\theta} + \ddot{\phi}) = a(a+b)\ddot{\phi}$

$$mx^2\ddot{\phi} + \frac{2}{5}ma(a+b)^2\ddot{\phi} - mgx \sin \phi = 0$$

$$\text{but } x = a + b, \text{ so } \quad mx\ddot{\phi} + \frac{2}{5}mx\ddot{\phi} - mg \sin \phi = 0 \quad \Rightarrow \quad \frac{7}{5}mx\ddot{\phi} - mg \sin \phi = 0$$

multiply thru by $\dot{\phi}$ and integrate with respect to time

$$\frac{d}{dt}\left\{\frac{7}{5}mx\frac{1}{2}\dot{\phi}^2 + mg \cos \phi\right\} = 0 \quad \text{so} \quad \frac{7}{10}x\dot{\phi}^2 + g \cos \phi = C$$

Initial conditions are $\phi = 0$, $\dot{\phi} = 0$ so $\dot{\phi}^2 = \frac{10g}{7x}(1 - \cos \phi)$

From (1) $\lambda_1 = mg \cos \phi - mx\dot{\phi}^2 = \frac{mg}{7}(17 \cos \phi - 10)$. So $\lambda_1 = 0$, when $\cos \phi = \frac{10}{17}$.