THE UNIVERSITY OF NEW SOUTH WALES

SCHOOL OF PHYSICS

EXAMINATION – JUNE/JULY 2005

PHYS2010 – MECHANICS

Time allowed – 2 hours

Total number of questions – 5

Answer ALL FIVE questions.

The questions are of equal value.

This paper may be retained by the candidate.

The following materials will be provided by the Enrolments and Assessments

Section:

Calculators.

All answers must be in ink.

Except where they are expressly required, pencils may only be used for

drawing, sketching or graphical work.

Damped Harmonic Motion

$$m\ddot{x} + b\dot{x} + kx = 0$$

$$x = Ae^{qt}$$

$$q = -\gamma \pm \sqrt{\gamma^2 - \omega_0^2}$$

$$\gamma = \frac{b}{2m}$$

$$\omega_0^2 = \frac{k}{m}$$

Forced Harmonic Motion

$$m\ddot{x} + b\dot{x} + kx = 0$$

$$x = A\cos(\omega t - \varphi)$$

$$A = \frac{F_0}{m\sqrt{(\omega^2 - \omega_0^2)^2 + 4\gamma^2 \omega^2}}$$

$$\tan \varphi = \frac{2\gamma\omega}{\omega_0^2 - \omega^2}$$

$$\omega_r^2 = \omega_0^2 - 2\gamma^2$$

$$Q = \frac{\sqrt{\omega_0^2 - \gamma^2}}{2\gamma}$$

Central field

$$U_{eff}(r) = \frac{M^2}{2mr^2} + U(r)$$

$$\varphi = \pm \int \frac{(M/r^2)dr}{\sqrt{2m[E - U_{eff}(r)]}}$$

$$t = \pm m \int \frac{dr}{\sqrt{2m[E - U_{eff}(r)]}}$$

Lagrangian

$$L = T - U$$
$$\frac{d}{dt} \frac{\partial L}{\partial \dot{q}_i} = \frac{\partial L}{\partial q_i}$$

A wedge of mass M with an angle ϕ is free to slide on a frictionless horizontal table. A solid ball of radius a and mass m is placed on the slope of the wedge. The contact between the ball and the wedge is perfectly rough.

- (a) Derive an expression for the total kinetic energy of this system.
- (b) Derive an expression for the Lagrangian of this system.
- (c) Use Lagrange's equations to find the equations of motion for this system.
- (d) Derive an analytic expression for the horizontal acceleration of the wedge with respect to the tabletop.
- (e) Discuss the dependence of the acceleration of the wedge on the radius of the sphere.
- (f) Find the wedge angle ϕ that produces the maximal wedge acceleration when the mass of the sphere is large compared with the mass of the wedge.

Part A

An inverse square law force is given by:

$$f(r) = -\frac{k}{r^2}$$

Substituting this into the orbit equations for a particle acted upon by a central force results in the following equation:

$$\frac{d^2u}{d\theta^2} + u = \frac{k}{mh^2}$$

where u=1/r, m is the mass of the particle and h is the angular momentum per unit mass.

- (a) Solve this equation for the orbit of a particle in an inverse square force field.
- (b) Show that the solution has the form of a general conic section.
- (c) From this (or otherwise) obtain expressions for the following in terms of the parameters describing the particle and its motion:
 - (i) the eccentricity of the orbit
 - (ii) the perihelion of the orbit
 - (iii) the aphelion of the orbit.
- (d) Show that for a particle orbiting in a central force, momentum is not conserved.

Part B

Two particles of mass m and M interact via a force that is directed along the line connecting the two particles.

- (e) Show that the motion of this physical system can be reduced to the motion of a single (hypothetical) particle in a central force.
- (f) Discuss the implications of the non-conservation of momentum in the solution of the central force problem for the two body system.

Part A

For the damped harmonic oscillator, the equation of motion can be written as:

$$m\ddot{x} + c\dot{x} + kx = 0$$

(a) explain all terms in this equation.

The equation can be solved by finding the roots of the corresponding subsidiary equation:

$$m\alpha^2 + c\alpha + k = 0$$

This results in three distinct types of solutions that represent three types of physical behaviour: overdamping, critical damping and underdamping.

(b) Explain each of these modes of physical behaviour. Use sketches to illustrate the motion of the particle in each case.

Part B

A new physical system is designed having the following equation of motion:

 $m\ddot{x} + c\dot{x} - kx = 0$

where m is the mass of a particle and c and k are positive constants.

- (c) From the corresponding subsidiary equation (or otherwise), find the solution to this equation of motion (Hint: use the solution of the damped harmonic oscillator as a guide).
- (d) How many distinct types of solution and hence physical behaviour, does this system exhibit? (i.e. does it have solutions that correspond to "overdamping, critical damping and underdamping"?).
- (e) Discuss the physical reasons for the difference in the physical behaviour of this system compared with the damped harmonic oscillator.

A velocity dependent force is given by:

$$\mathbf{\underline{F}} = a(\dot{y}\mathbf{\underline{i}} - \dot{x}\mathbf{\underline{j}})$$

where a is a constant and **i** and **j** are the unit vectors in the x and y directions, respectively.

(a) Using Newton's second law of motion (or otherwise), show that the above force results in the following equations of motion for a particle of mass, m, moving in two dimensions(x-y plane):

$$\ddot{x} = -\left(\frac{a}{m}\right)^2 x + C$$
$$\ddot{y} = -\left(\frac{a}{m}\right)^2 y + D$$

where C and D are integration constants.

(b) Show that the general solution to the above equations of motion has the form:

$$x = A\cos(\omega_x t + \phi) + E$$
$$y = B\sin(\omega_y t + \phi) + F$$

Initially, the particle is at the origin (0,0) and it has a velocity:

 $\underline{v_o} = v_o \underline{j}$

- (c) Using these conditions plus restrictions imposed by the equations of motion, show that:
 - (i) The angular frequencies, ω_x and ω_y , are equal.
 - (ii) The phases, ϕ and ψ , are both equal to zero.
 - (iii) The amplitudes are equal and opposite.
- (d) Hence, determine the values of all of the unknown constants in the general solution (i.e. find: A, B, ω_x , ω_y , ϕ , ψ , E and F).
- (e) Describe the orbit taken by the particle.
- (f) Determine the equation of the orbit described by the solution.

Note: In this question, Part A and Part B are **not** connected. Please answer **both** parts.

Part A

(a) Find the location of the centre of mass of a uniform solid hemisphere of radius a. Show all your working.

Part B

(b) Show that the Lagrangian for a general vibrating system is given by:

$$L = \sum_{j} \sum_{k} \frac{1}{2} \left(M_{jk} \dot{q}_{j} \dot{q}_{k} - K_{jk} q_{j} q_{k} \right)$$

Explain the meaning of all symbols in this equation.

- (c) Derive the equations of motion of this system.
- (d) Hence show that the n roots of the secular determinant are the squares of the normal frequencies of the system.