Solution Question 1 (a) Both 1121 and 1131:

(i)
$$\mathbf{v} = \frac{d\mathbf{r}}{dt} = \left(\frac{d}{dt}\right) (3.00\hat{\mathbf{i}} - 6.00t^2\hat{\mathbf{j}}) = \boxed{-12.0t\hat{\mathbf{j}} \text{ m/s}}$$
$$\mathbf{a} = \frac{d\mathbf{v}}{dt} = \left(\frac{d}{dt}\right) (-12.0t\hat{\mathbf{j}}) = \boxed{-12.0\hat{\mathbf{j}} \text{ m/s}^2}$$
(ii)
$$\mathbf{r} = (3.00\hat{\mathbf{i}} - 6.00\hat{\mathbf{j}}) \text{m; } \mathbf{v} = -12.0\hat{\mathbf{j}} \text{ m/s}$$

Solution Question 1 (b) Both 1121 and 1131:

a = 3.00 m/s²; v_i = 5.00 m/s; r_i = 0 + 0 (i) $r_f = r_i + v_i t + \frac{1}{2} a t^2 = \left[5.00t + \frac{1}{2} 3.00t \right] m$ $v_f = v_i + a t = \left(5.00 + 3.00t \right) m/s$ (ii) $t = 2.00 \text{ s}, r_f = 5.00(2.00) + \frac{1}{2}(3.00)(2.00)^2 = (10.0 + 6.00) m$ so $x_f = 10.0 \text{ m}, y_f = 6.00 \text{ m}$ $v_f = 5.00 + 3.00(2.00) = (5.00 + 6.00) m/s$ $v_f = 5.00 + 3.00(2.00) = (5.00 + 6.00) m/s$ $v_f = [v_f] = \sqrt{v_{xf}^2 + v_{yf}^2} = \sqrt{(5.00)^2 + (6.00)^2} = 7.81 \text{ m/s}$

Solution Question 1 (c) PHYS1131 only:

(i)
$$a_{t} = \boxed{0.600 \text{ m/s}^{2}}$$

(ii) $a_{r} = \frac{v^{2}}{r} = \frac{(4.00 \text{ m/s})^{2}}{20.0 \text{ m}} = \boxed{0.800 \text{ m/s}^{2}}$
(iii) $a = \sqrt{a_{t}^{2} + a_{r}^{2}} = \boxed{1.00 \text{ m/s}^{2}}$

$$\theta = \tan^{-1} \frac{a_r}{a_t} = \boxed{53.1^\circ \text{ inward from path}}$$

i) If non-conservative forces do no work, mechanical energy is conserved.

ii) If the external forces on a system are zero, the momentum of that system is conserved.

iii) Consider first the swing before the collision. Let the mass have speed v just before the collision. In this phase, air resistance is negligible, so non-conservative forces do no work, therefore mechanical energy is conserved, which we may write as

$$\Delta E = \Delta K + \Delta U = 0$$

(¹/₂ mv² - 0) + (0 - mgR) = 0
v² = 2gR
v = $\sqrt{2gR}$

Next, consider the collision. Let the combined object have speed V after the collision.



1131 The forces between the two objects during the collision will be much greater than the external force (friction) in the horizontal direction. Therefore momentum (in the x direction) is approximately conserved.

1121 In the x direction, the only external force acting during the collision is friction, which we are told is negligible. Therefore momentum in the x direction is conserved.

 $p_{initial} = p_{final}$ mv = 2mV. Rearranging and substituting for v: $V = v/2 = \sqrt{gR/2}$

Finally, consider the rising arc. During this phase, air resistance is still negligible, so non-conservative forces do no work, therefore mechanical energy is conserved, which we may write as

$$\Delta E = \Delta K + \Delta U = 0$$

(0 - ½ (2m)V²) + (2mgD - 0) = 0. Rearranging gives
D = V²/2g and substitution gives
= R/4

1131 only

iv) In both states, there is no kinetic energy.

 $\Delta E = \Delta K + \Delta U = 0 + \Delta U$ Taking the floor as the zero for gravitational potential energy,

$$= 2mgR/4 - mgR = -mgR/2.$$

The internal forces during the collision are non-conservative, and they do negative work. (The ball is irreversibly deformed, so work around a closed loop is not zero.) OR: Mechanical energy is lost as heat and in plastic deformation of the ball (and even sound).

Newton's second law applied to *m*:

$$T_2 - mg = ma$$

so
$$T_2 = m(a + g)$$
(1)

Let the pulleys turn with angular acceleration α in the clockwise direction. Newton's second law for rotation applied to the disk:

$$\Sigma \tau = I\alpha \qquad \text{so}$$

$$RT_1 - rT_2 = I\alpha \qquad (2)$$

$$\alpha = \frac{RT_1 - rT_2}{I} \quad \text{clockwise} \left(\text{or} - \frac{RT_1 - rT_2}{I} \text{ anticlockwise} \right)$$

Because the cord doesn't slip, $\alpha = a/r$. Making that substitution and using (1), (2) becomes

$$RT_{1} - rm(a + g) = Ia/r$$

$$a(I/r + rm) = RT_{1} - rmg$$

$$a = \frac{RT_{1} - rmg}{I/r + rm}$$
which is fine for an answer, though we might 'neaten' to
$$a = \frac{RT_{1}/rm - g}{I/mr^{2} + 1}$$

Question 4.

(a) (i) 0 °C as in thermal equilibrium with ice at atmospheric pressure.(ii)

$$Q = mL$$

= 0.00180 × 3.33 × 10⁵
= 599J (3 sig fig)

(iii) Q lost by lead = Q gained by water, ice and copper $m_L c_L (255 - T_f) = 599 + (m_c c_c + (m_w + m_i)c_w)(T_f - 0)$ $97.5(255 - T_f) = 599 + 716 \times T_f$

$$T_f = \frac{24263.5}{97.5 + 716}$$
$$T_f = 29.8^{\circ}C$$

(b) (i)

$$n = \frac{m}{M} = \frac{3000}{32} = 93.75$$

$$A = 1.00m^{2} \Rightarrow V = 1m^{3}$$

$$PV = nRT$$

$$\Rightarrow P = \frac{nRT}{V}$$

$$= \frac{93.75 \times 8.314 \times (273 - 70)}{1.00}$$

$$= 158225.8 \text{ Pa}$$

$$= 158 \text{ kPa}$$

(ii)
$$m = \frac{M}{N_A} = \frac{32 \times 10^{-3}}{6.022 \times 10^{23}} = 5.3138 \times 10^{-26} \text{ kg}$$

 $\frac{3}{2}k_BT = \frac{1}{2}m\overline{v^2}$
 $\overline{v^2} = \frac{3 \times 1.381 \times 10^{-23} \times (273 - 70)}{5.3138 \times 10^{-26}}$
 $= 158271$
 $\Rightarrow v_{rms} = 398 \text{ m/s}$

1131 Only.

(iii)
$$E_{int} = \frac{f}{2}nRT$$

 $f = 5$ (3 translational and 2 rotational at -70° C)
 $E_{int} = \frac{5}{2} \times 5 \times 8.314 \times (273 - 70)$
.
 $= 21100J$

(c) (i)
$$W = -\int_{1}^{3} P dV$$

= -(3 - 1) × 3 × 1.01 × 10⁵
= -606 kJ

(ii) isothermal $\Rightarrow \Delta E_{intD \rightarrow A} = 0$

(iii)
$$\begin{array}{l} \Delta E_{int} = Q + W \\ \Delta E_{intA \rightarrow B} = 400 - 606 = -206 kJ \end{array}$$

$$\begin{split} W_{C \to D} &= -\int_{5.79}^{3.0} 1.01 \times 10^5 dV = 282kJ \\ \Delta E_{intC \to D} &= 407 + 282 = 689kJ \\ \Delta E_{intB \to C} &= -(\Delta E_{intC \to D} + \Delta E_{intD \to A} + \Delta E_{intA \to B}) \\ &= -(689 + 0 - 206) \\ &= -483kJ \\ \end{split}$$
Alternatively they could calculate $W = -\int PdV = \Delta E_{int}$
with PV^{γ} = constant = 1898.
To solve the integral substitute in $P = 1898V^{\gamma}$.
As it is an ideal monatomic gas $\gamma = 1.67$.

(iv)
$$PV^{1.67} = 3 \times 1.01 \times 10^5 \times 3^{1.67} = 1.90 \times 10^6$$

 $c_P = f + 2 = 5$

1131 only

$$\gamma = \frac{c_P}{c_V} = \frac{f+2}{f} = \frac{5}{3} = 1.67$$

 $PV^{\gamma} = \text{const}$ can be evaluated at any point eg. P = 3.0 atm, V = 3.0 m³

Q5

30 marks 1131 / 25 marks 1121

(a)

(i) For each spring we have F = -kx where F is the restoring force and x the displacement from equilibrium. There are 4 springs, and so the SHM is governed by:

 $m_c \ddot{x} = -4kx$ where m_c is the mass of the car plus occupants = (M+2m).

Thus $\omega^2 = 4k/(M+2m)$ governs the angular frequency of the motion.

Then $f = \omega/2\pi = 1/2\pi \cdot \sqrt{4k/m_c} = 1/2\pi \cdot \sqrt{\frac{4 \cdot 8000}{1500 + 2 \cdot 80}} = 0.6988 \text{ s}$

Thus f=0.70s to 2SF

(ii) We simply replace $m_c=M+2m$ by M when there are no occupants in the car.

Thus
$$f = \omega/2\pi = 1/2\pi \cdot \sqrt{4k/m_c} = 1/2\pi \cdot \sqrt{\frac{4 \cdot 8000}{1500}} = 0.7351 \text{ s}$$

So *f*=0.74s to 2SF

(iii)



Full derivation not necessary, but answer should show sinusoidally damped displacement and velocity, with velocity at a maximum (either positive or negative) at t=0, with displacement 0 at t=0. Displacement and velocity are $\pi/2=1/4$ of a cycle out of phase. [strictly speaking this doesn't hold as time increases, but we are in lightly damped case, so the discrepancy is small]. Successive peaks should only be a little smaller than the previous one.

$$x = A\sin(\omega t)e^{-\beta t} \text{ with } x = 0 \text{ at } t = 0$$

Full derivation: $v = \dot{x} = \omega A\cos(\omega t)e^{-\beta t} - \beta A\sin(\omega t)e^{-\beta t}$
 $\therefore v = \omega A\cos(\omega t)e^{-\beta t} - \beta x$

Lightly damped so that damping constant β is small.

(b)

(i) We have
$$y_1 = A\sin(kx - \omega t)$$
$$y_2 = A\sin(kx + \omega t)$$

where the – wave travels in the +*x*-direction and the + wave travels in the –*x* direction.

 y_1 and y_2 are the displacements from equilibrium.

		$y = y_1 + y$	=	$A\sin(kx - \omega t) + A\sin(kx + \omega t)$
(ii)	Then their sum		=	$\frac{2A\sin(\frac{kx+kx}{2})\cos(\frac{\omega t+\omega t}{2})}{2A\sin(kx)\cos(\omega t)}$

(iii) This is a standing wave because the spatial and time components are separated. The wave is not travelling along the *x*-direction, but each particle in the medium is simply oscillating about its position in phase (or anti-phase) with every other particle, and with amplitude dependent on its position.

(iv) General form of graph. Axes are distance (x-direction) and displacement (y-direction), with different plots showing different times. Note that quantitative values are not needed. The plot below actually assumes $A = k = \omega = 1$. Amplitude is 2A and half-wavelength is π/k . The period is $2\pi/\omega$.



Note: if the student used $y_1 = A\cos(kx - \omega t)$ $y_2 = A\cos(kx + \omega t)$ for the travelling wave their derivation they should then obtain $y = 2A\cos(kx)\cos(\omega t)$, and their graph above should show an anti-node at the origin, x=0.

(c)

(i) The open end is an antinode and the closed end is a node. First resonance then given by $L_1 = \lambda/4$, $\pm \xi$. Second resonance is given by $L_2 = 3\lambda/4$, $\pm \xi$. In general the *n*-th resonance is given by $L_n = (2n-1)\lambda/4$, $\pm \xi$.

The distance between 2 successive resonances is simply $\Delta L = \lambda/2$

Since $v = f\lambda$ then $v = f2\Delta L = 376 \cdot 2 \cdot [56.2 - 10.2]/100 \text{ m/s} = 345.9 \text{ m/s}.$

Hence v=346 m/s to 3SF.

(ii) Each resonance is separated by $\Delta L = \lambda/2$ so that the next resonance is at 56.2+[56.2-10.2]=102.2cm

(iii) For a closed pipe at both ends then resonance is given when $n\left(\frac{\lambda}{2}\right) = L_n$ since there are a whole number of half-wavelengths for a node at each end. Given L=102.2cm, then $n = 2L/\lambda$ with $\lambda = \nu/f = 345.9/376 = 0.920$ m.

Then we find that $n = 2. \cdot 102.2/92.0 = 2.22$.

Thus the closest node has n=2, for which $L = n\lambda/2 = 2/2 \cdot 0.920 = 0.920 \text{ m} = 92 \text{ cm}$.

Thus the piston needs to be moved 102.2-92.0=10.2cm nearer to the other closed end for the nearest resonance position.