

QUESTION 1. (7.5 marks)

a) Show that the transformation

$$Q = p + iaq \quad \text{and} \quad P = \frac{p - iaq}{2ia}$$

is a canonical.

b) Find the generating function of type $F_2(q,P)$ for the transformation where

$$p = \frac{\partial F_2(q,P)}{\partial q} \quad \text{and} \quad Q = \frac{\partial F_2(q,P)}{\partial P}$$

c) If the Hamiltonian is $H = \frac{1}{2}(p^2 + a^2q^2)$, find the new Hamiltonian $K(Q,P)$ generated by the transformation.

d) Use Hamilton's equations of motion to find the equations of motion for $K(Q,P)$.

e) Solve these equations of motion to find the time evolution of Q and P .

f) If u is a function of q,p,t write down the Poisson bracket form for the equation of motion for u .

g) Hence derive the Poisson bracket equations of motion for q and p .

~~$$H = \frac{1}{2}(p^2 + a^2q^2)$$~~

~~$Q = p + iaq$~~

~~$$Q = p + iaq$$~~

~~$$2iaP = p - iaq$$~~

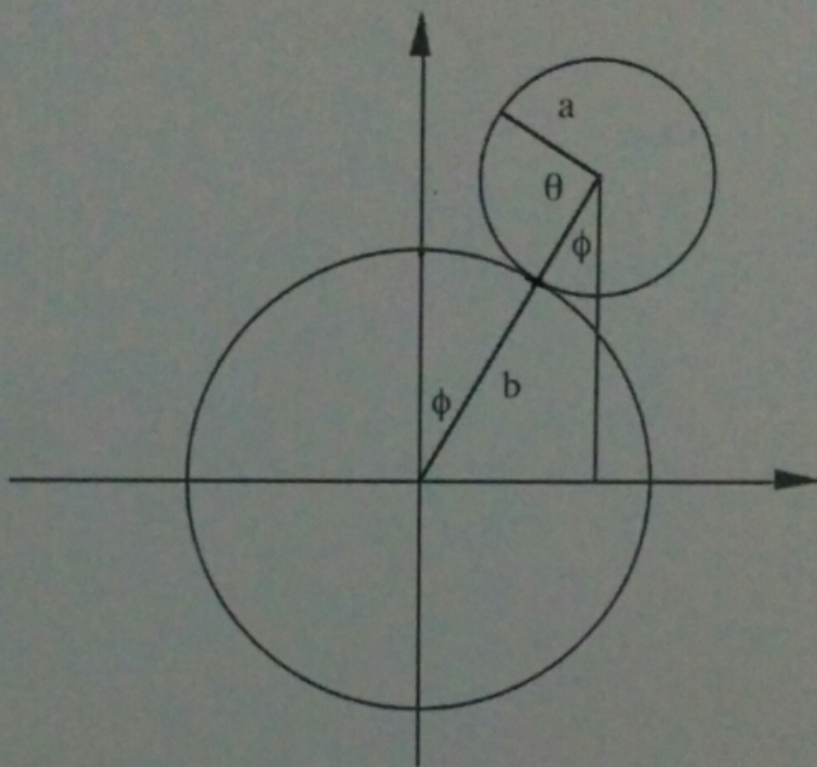
~~$$p = Q - iaq$$~~

~~$$Q = Q - 2iaP - iaq$$~~

~~$$\int p \dot{q} dt$$~~

QUESTION 2. (7.5 Marks)

A sphere of radius a and mass m rests on top of a fixed sphere of radius b . The first sphere is slightly displaced so that it rolls without slipping down the second sphere. Where will the first sphere leave the second sphere?



- Determine the kinetic and potential energy of the moving sphere in polar coordinates and find the Lagrangian for this system.
- Identify the constraints and find the equations of constraint.
- Use the method of Lagrange's undetermined multipliers to obtain the equations of motion for the system in spherical polar coordinates.
- Show that eliminating the no slipping constraint gives the following equation for ϕ

$$\frac{7}{3}x\ddot{\phi} - g\sin\phi = 0$$

- Determine the initial conditions for $\dot{\phi}(\phi)$.
- If $\lambda_1 = mg\cos\phi - mx\dot{\phi}^2$, solve for λ_1 .
- Explain the physical meaning of the multiplier λ_1 .